



A Process Oriented Approach to USB Driver Development



Fred Barnes and Carl Ritson, Systems Research Group
Computing Laboratory, University of Kent, UK
{ F.R.M.Barnes , C.G.Ritson } @kent.ac.uk

University of
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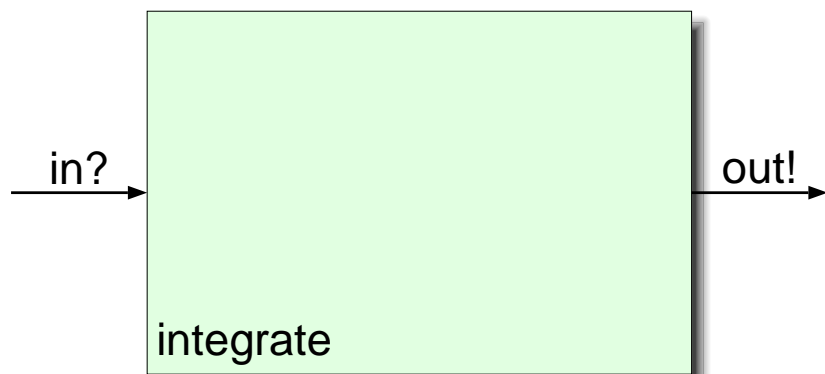
- A brief introduction to occam- π
- The RMoX operating system
- USB hardware
- Process-oriented USB (in layers)
- Conclusions and further work

A Brief Introduction to **occam-pi**

- ▶ **Process oriented** language: systems built from layered networks of communicating processes
 - semantics primarily from Hoare's **CSP** (communicating sequential processes)
 - incorporates ideas of **mobility** from Milner's **π -calculus**
- ▶ Language elements include:
 - **channels**: one-to-one, one-to-any, any-to-one, any-to-any synchronous unbuffered communication
 - **barriers**: synchronisation between multiple processes (CSP event)
 - **mobiles**: movement semantics for **data**, **channel-ends**, **processes**
 - **dynamic process creation**: for building dynamically evolving systems
- ▶ Strong **formal** concurrency mechanisms make **occam- π** suitable for building many types of system, both simple and complex

Simple Processes

Serial integrator:

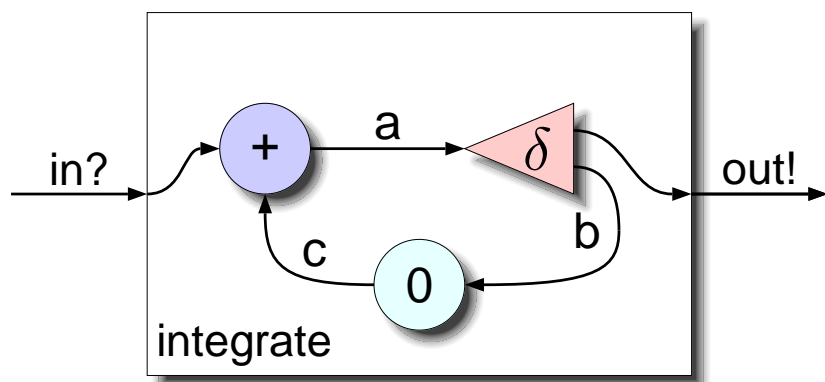


```

PROC integrate (CHAN INT in?, out!)
  INITIAL INT total IS 0:
  WHILE TRUE
    INT x:
    SEQ
      in ? x
      total := total + x
      out ! total
  :

```

Parallel integrator:



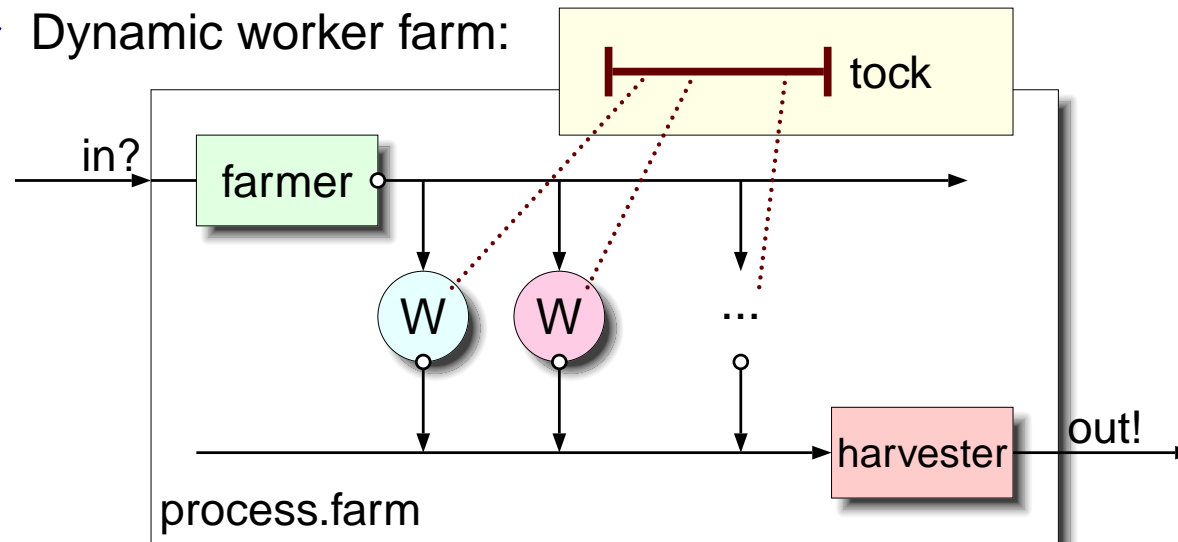
```

PROC integrate (CHAN INT in?, out!)
  CHAN INT a, b, c:
  PAR
    plus (in?, c?, a!)
    delta (a?, out!, b!)
    prefix (0, b?, c!)
  :

```

Less Simple Processes

Dynamic worker farm:



one-to-one:

any-to-one:

one-to-any:

any-to-any:

Channel-type primer:

- bundles of channels declared as a **record-type**
- **mobile** ends (moved around for network reconfiguration)
- both **shared** and **unshared** ends (supporting one-to-one, ..., any-to-any)

- Generally refer to the two ends as **client** and **server**, denoted '!' and '?' respectively — because that's the most common usage pattern, but not enforced

occam-pi and Related Tools

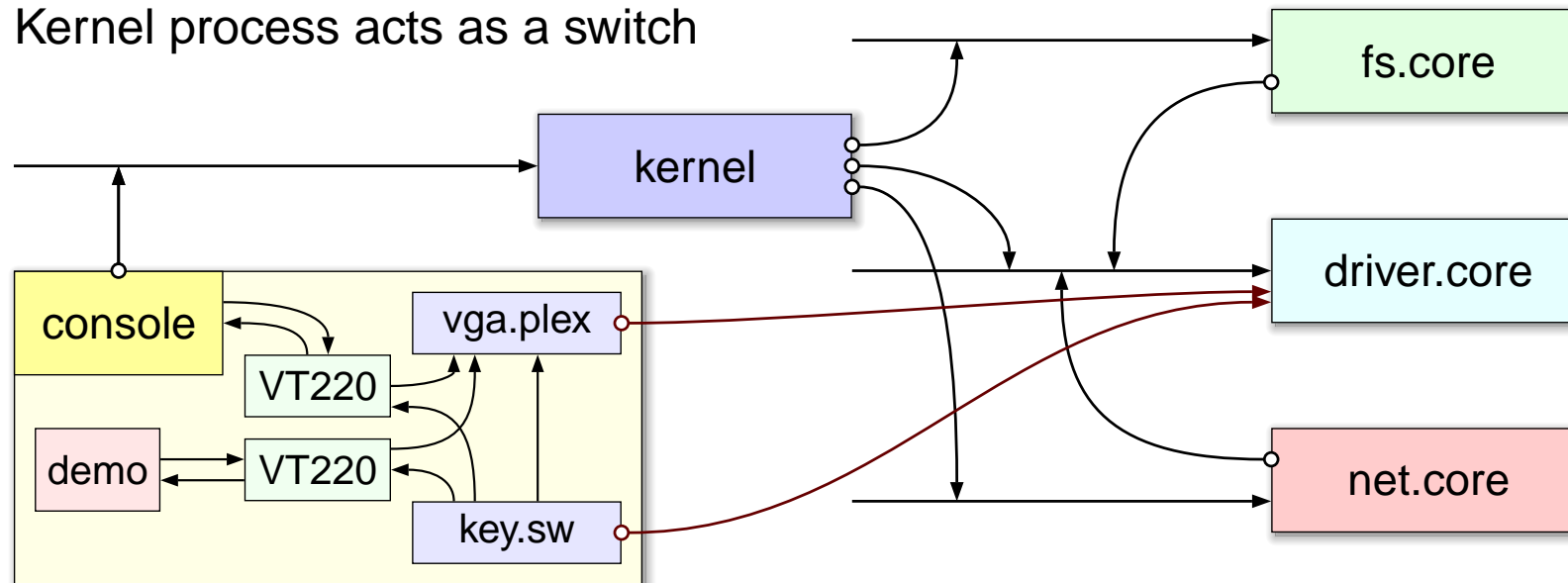
- ▶ For occam- π , have:
 - **KRoC**: compiles down to i386 native code, ~50ns context-switch
 - **Transterpreter**: portable interpreter, ~1us context-switch
- ▶ For expressing CSP ideas in other languages:
 - **JCSP** and **CTJ** for Java
 - **C++CSP** for C++
 - similar things cropping up here and there (concurrent programming is of increasing interest, again)
- ▶ The memory footprint for occam- π parallel processes is comparatively small:
 - can handle **millions** of simple processes on a modern desktop PC

The RMoX Operating System

- ▶ RMoX is an operating-system built using occam- π , utilising concurrency at its lowest level — currently for Intel Pentium based hardware
- ▶ EPSRC funded project (EP/D061822/1) to develop RMoX for PC/104 systems
- ▶ Theory is: build an OS out of layered networks of communicating concurrent processes, and it will be:
 - **scalable**: from small embedded systems, through general-purpose (desktop) computers, up to massively parallel supercomputers
 - **reliable**: freedom from race-hazard and aliasing errors
 - **efficient**: low overheads (sub 100ns context-switch), no need for heavyweight memory-management (maybe)

The RMOX Operating System

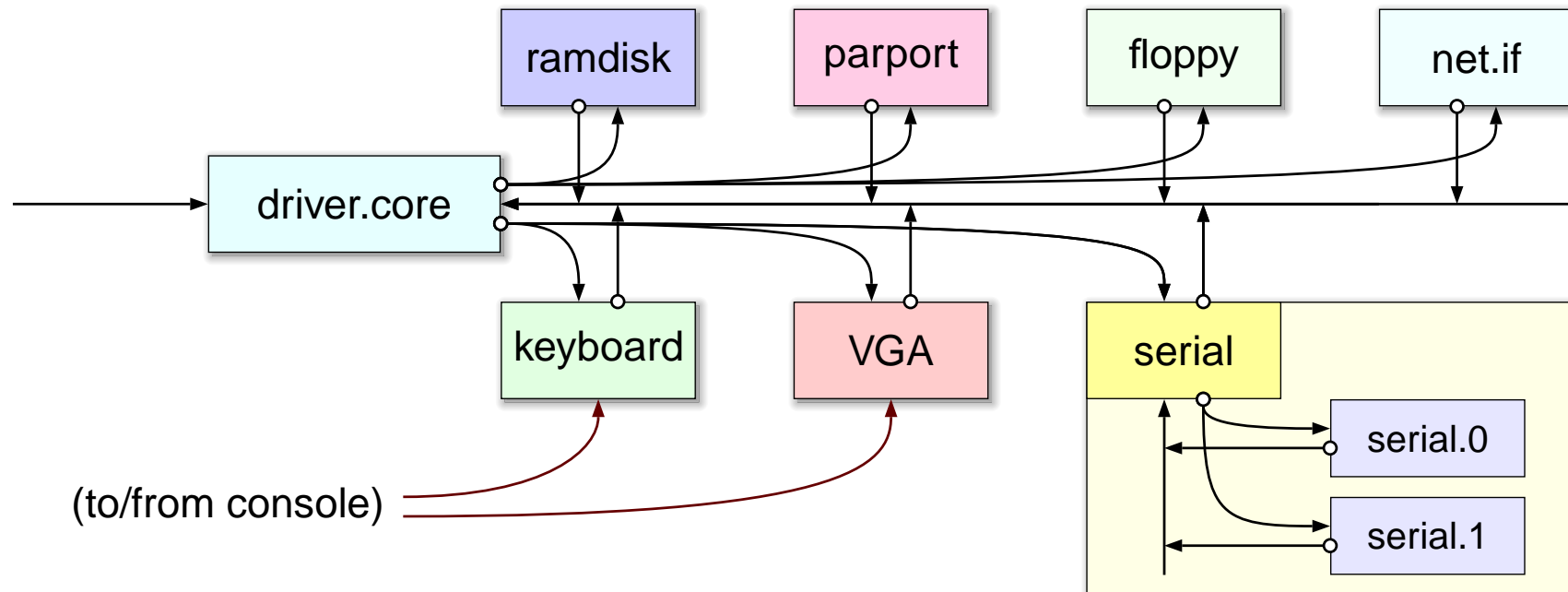
- System design is fairly straightforward — operating-systems provide services
- Kernel process acts as a switch



- Console process provides a basic user-interface
- Connections within dynamically formed and dismantled as required

The RMOX Operating System

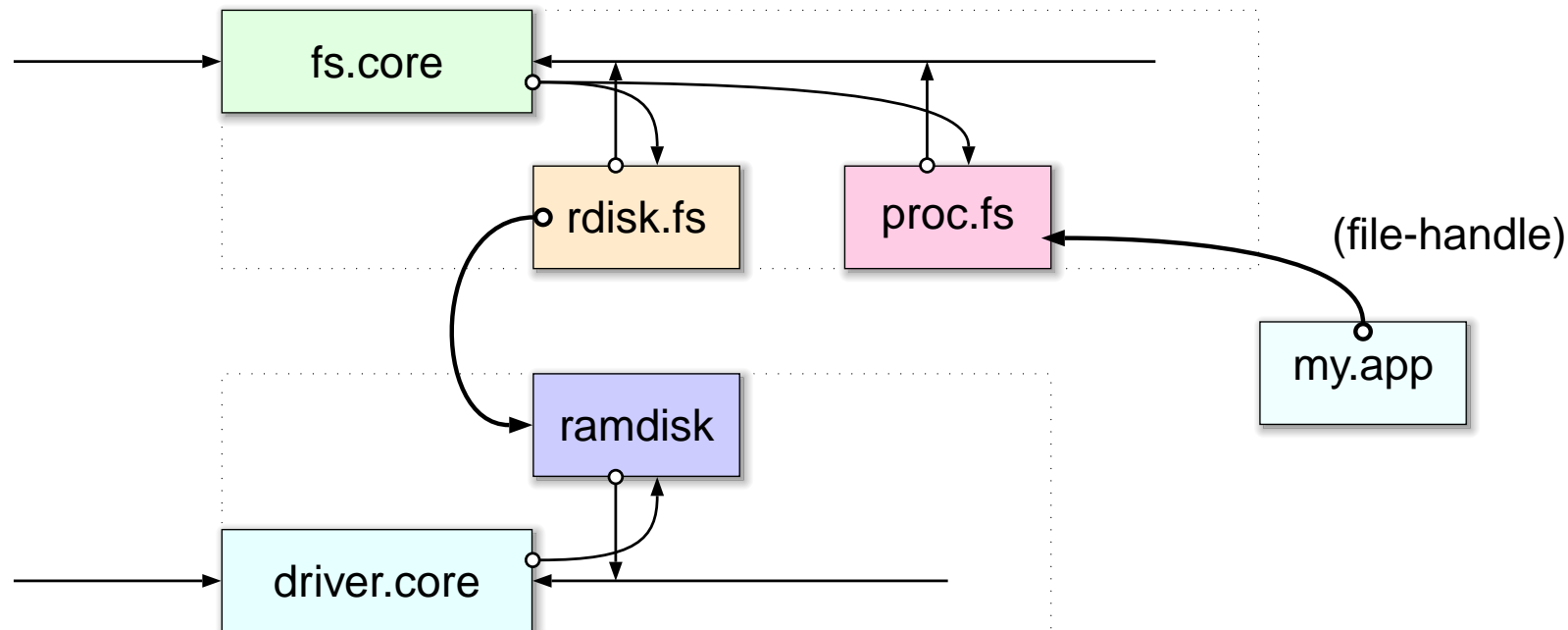
- The various “core” components utilise internal concurrency



- Drivers themselves may be concurrent internally
- Some drivers mostly complete, others under construction

The RMoX Operating System

- Largely a **client-server** architecture internally — deadlock free

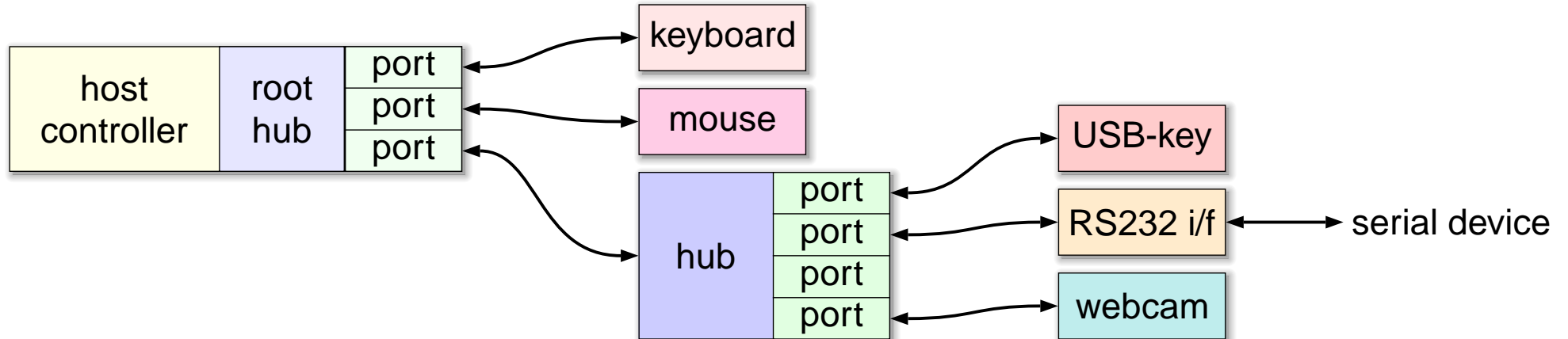


- Device drivers are the bottom-level 'server' components
- Process networks for things such as PCI and USB drivers reflect hardware organisation — not a complex mass of sequential code!

USB Hardware

- ▶ USB, the **Universal Serial Bus**, is a 4-wire half-duplex peripheral interconnect
 - supports devices at three speeds: 1.5, 12 and 480 MBps
 - bus is strictly controlled: single **host controller** polls devices and offers bandwidth for transfers — UHCI, EHCI and OHCI standards say how

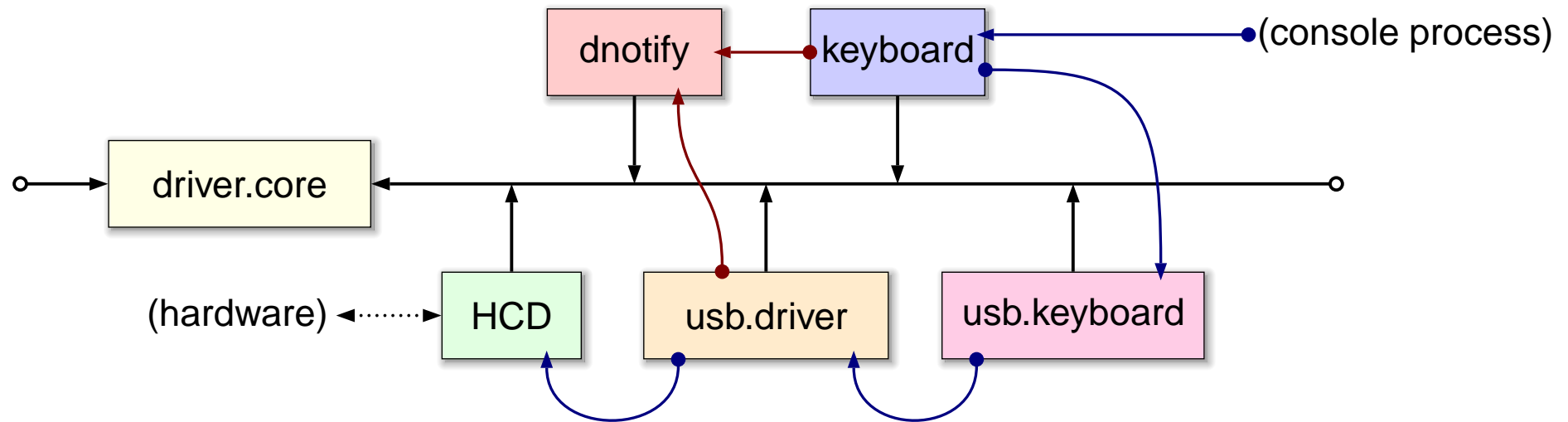
- ▶ Hardware structure is a tree:



- ▶ Devices can be added and removed randomly — software must cope!
- ▶ Range of devices is complex: simple peripherals, legacy interfaces, networking, ...

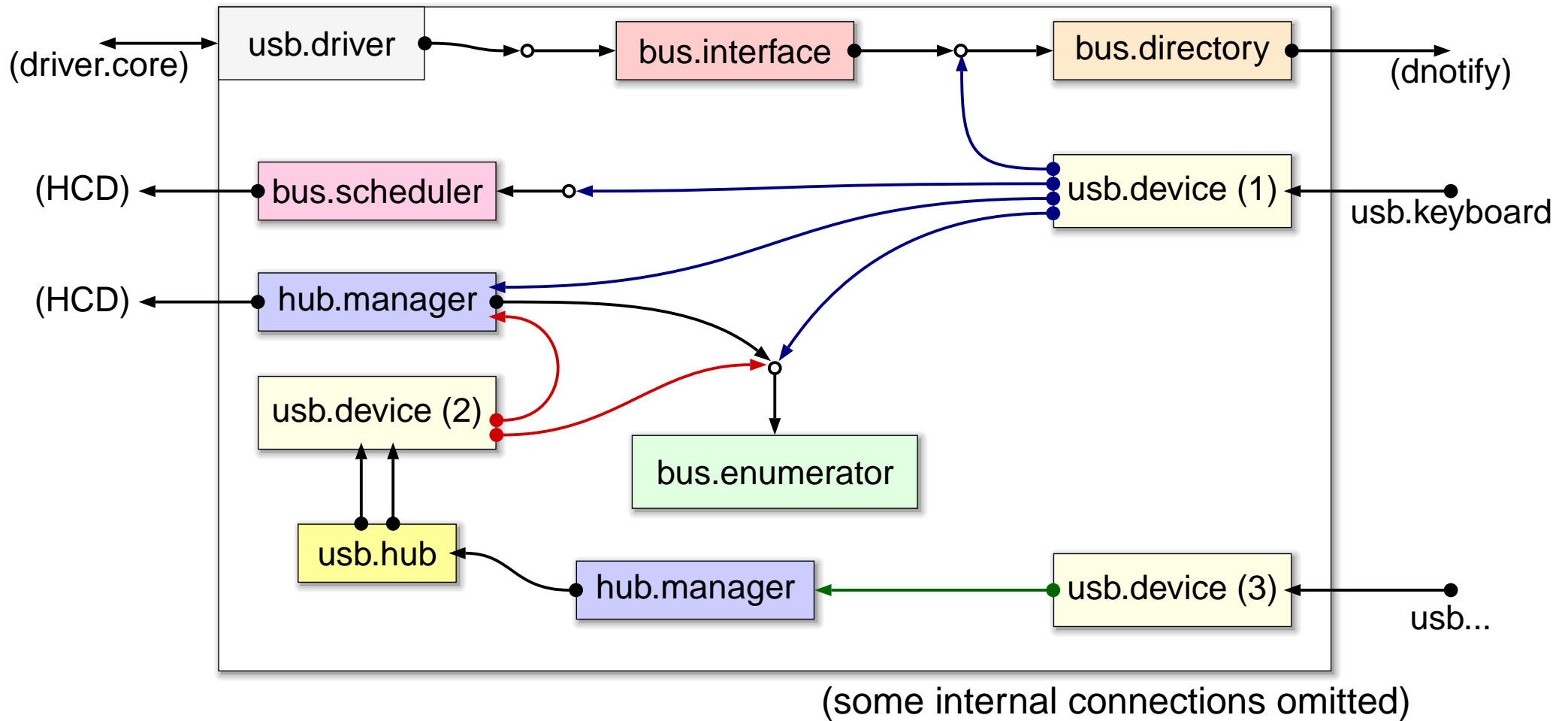
Process Oriented USB

- USB infrastructure lies mostly in the “driver.core”:



- **Device-notify** driver acts as a registration point, indicating when new USB devices are connected — routes connections between relevant device
- The **usb.driver** acts as a coordinator, with processes representing the physical structure — created and destroyed dynamically

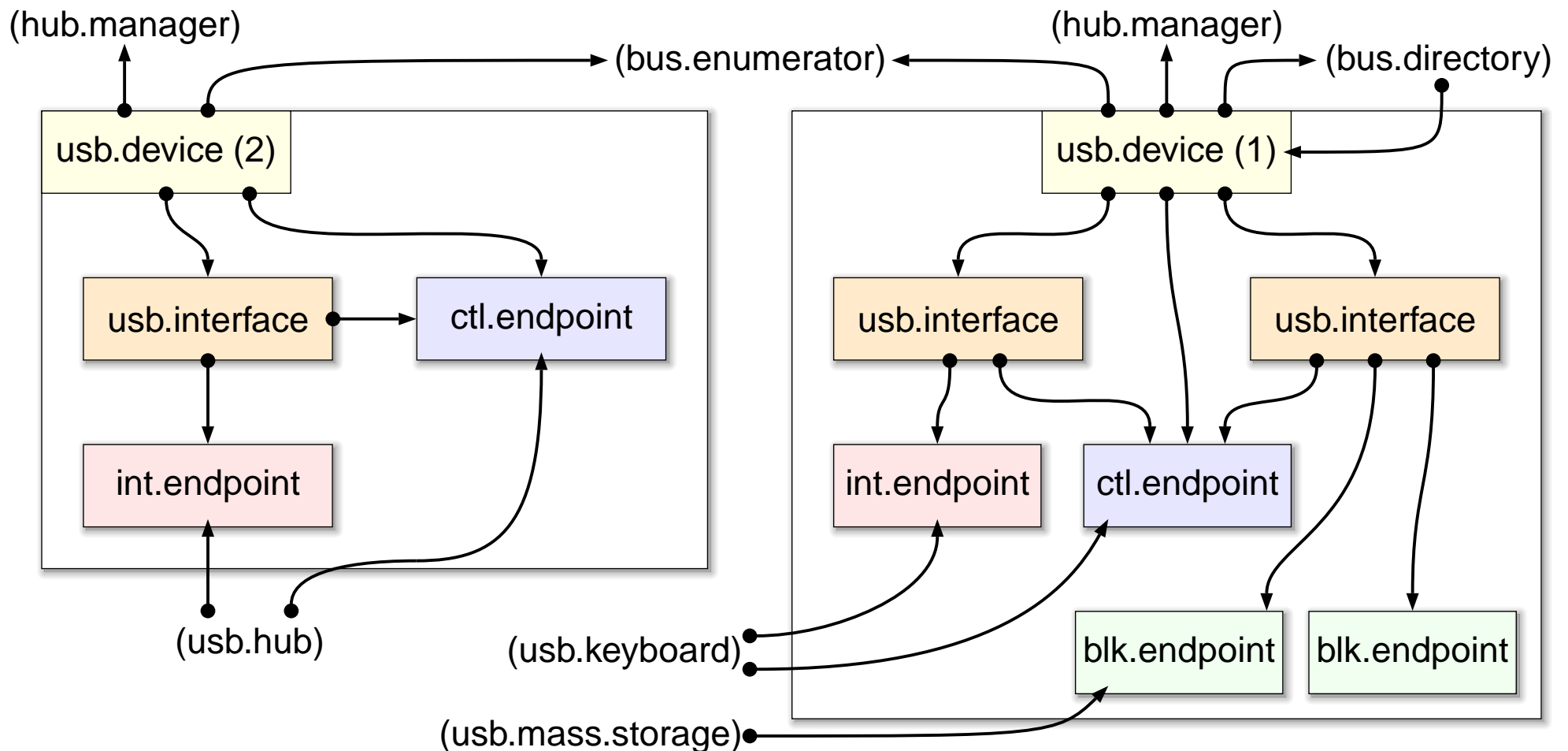
Process Oriented USB



➤ Structure grows and shrinks dynamically as devices are added and removed

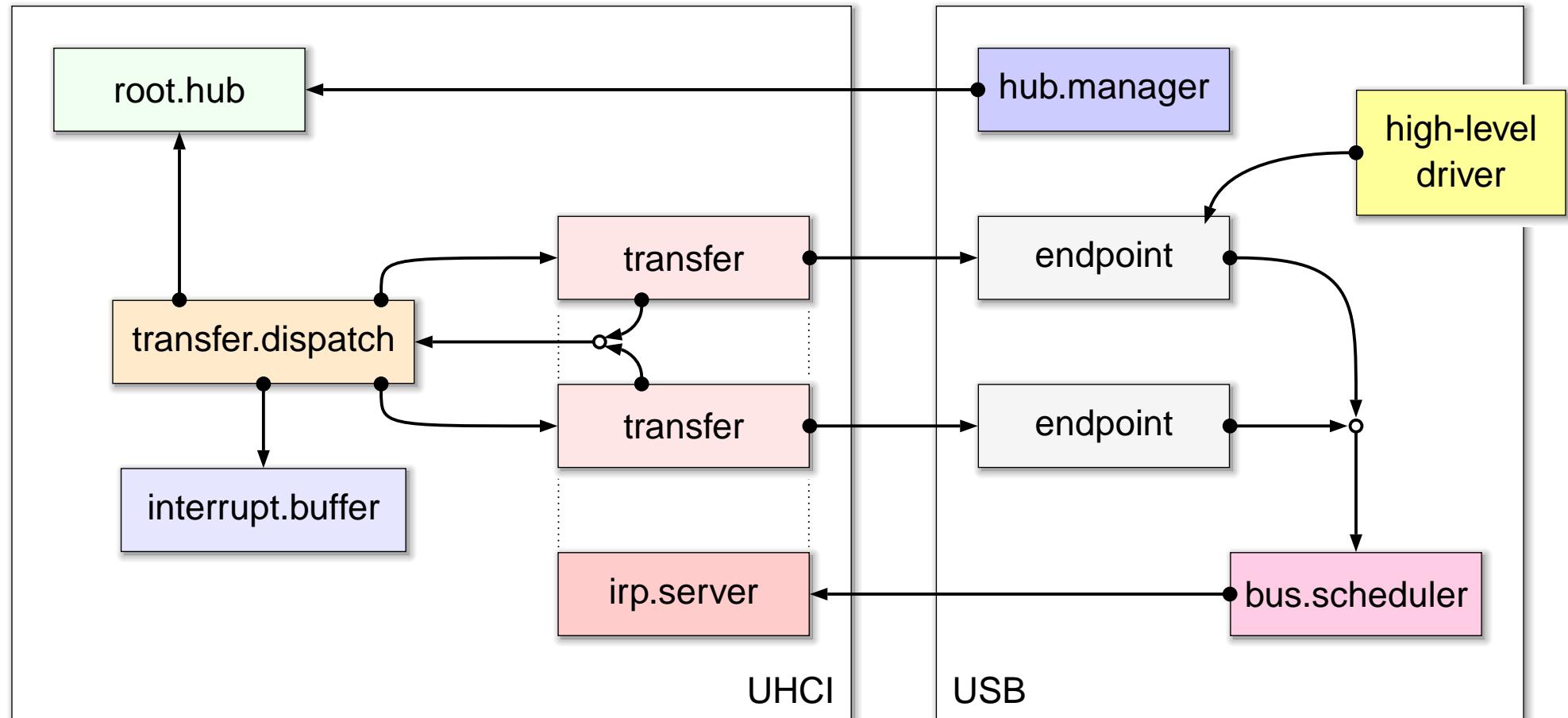
Process Oriented USB

- ▶ The **usb.device** processes have their own internal structure, reflecting the logical structure of USB devices (**interfaces** and **endpoints**):



Process Oriented USB

- ▶ The last puzzle piece is the linkage between the various **endpoint** processes and the underlying **host controller**:



Conclusions

- The resulting process network for any modest USB setup will be non-trivial (several hundred processes)
 - but built safely from **simple** self-contained components, assembled in a way which is **understandable**
- Software structure reflects hardware organisation
- Concurrency is a significant advantage for programming — a single device-driver (e.g. USB keyboard) can interact with multiple endpoints without complex coding
- Some care required in shut-down when a device is unplugged
 - dummy processes **forked** to service requests, preventing deadlock

Further Work

- USB stack itself works well (and, we expect, efficiently)
- Currently lacking higher-level components to use the underlying devices
 - have a working **USB keyboard** and can drive **USB audio** devices with wave data from **USB storage** devices (raw-blocks)
- Usage example is given in the paper, including the code that USB device-drivers use to connect and interface to the bus
- Ongoing development for **multi-processor** support, next steps will be proper **file-system** support
- Essentially open-source software, so any development effort very welcome!
- Questions?